

# Method for frame removal detection in static camera surveillance video

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## Objective of the study:

- New method for passive protection of a surveillance camera video from a video fragment deletion attack

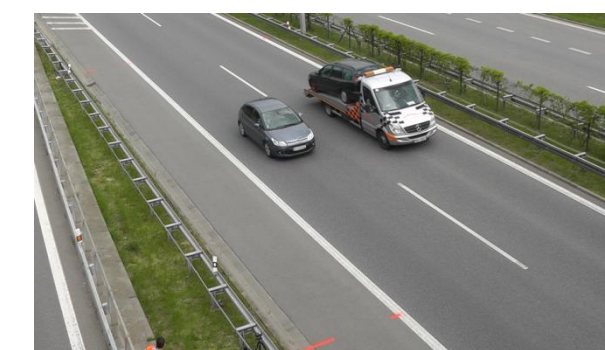
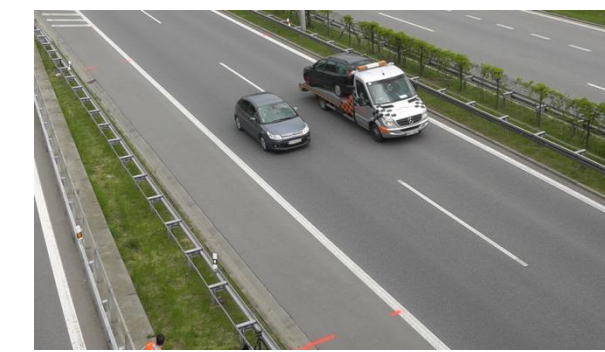
## The essence of the method:

- The method is based on the construction of local features for the samples of two consecutive frames, followed by a multilayer neural network classification. Post-processing and calculation of statistics based on the results of the classification helps to decide whether a given pair of frames is sequential or a number of frames were cut between them

## Benefits:

- Experiments show the efficiency of detection the fact of a fragment removal even from stationary scenes, when such a deletion is visually imperceptible

## Experiments



sequential frames



nonsequential frames



Confidence image for nonsequential frames

## Frame removal detection based on interframe local feature analysis

- feature calculation

for every sample of the current frame  $x_t(i, j)$

$$\bar{y}_t(i, j) = \{f(x_t(i-k, j-l), x_{t-1}(i-m-k, j-n-l))\}$$

$$f(x_t, x_{t-1}) = \sum_{c=1..3} (x_t^c - x_{t-1}^c)^2$$
 - the distance between pixel values

$$m, n \in [-r_c, r_c] \quad k, l \in [-r_a, r_a]$$

feature vector length –  $n_f = (2r_c + 1)^2 \cdot (2r_a + 1)^2$

- MNN classification

pixel-wise classification

2 inner layers (of size  $2n_f + 1$  and  $n_f$ ), softmax AF

classes: "cut" and "sequential"

output is the confidence value for "cut" class

for each pair of sequential frames "confidence image" is formed

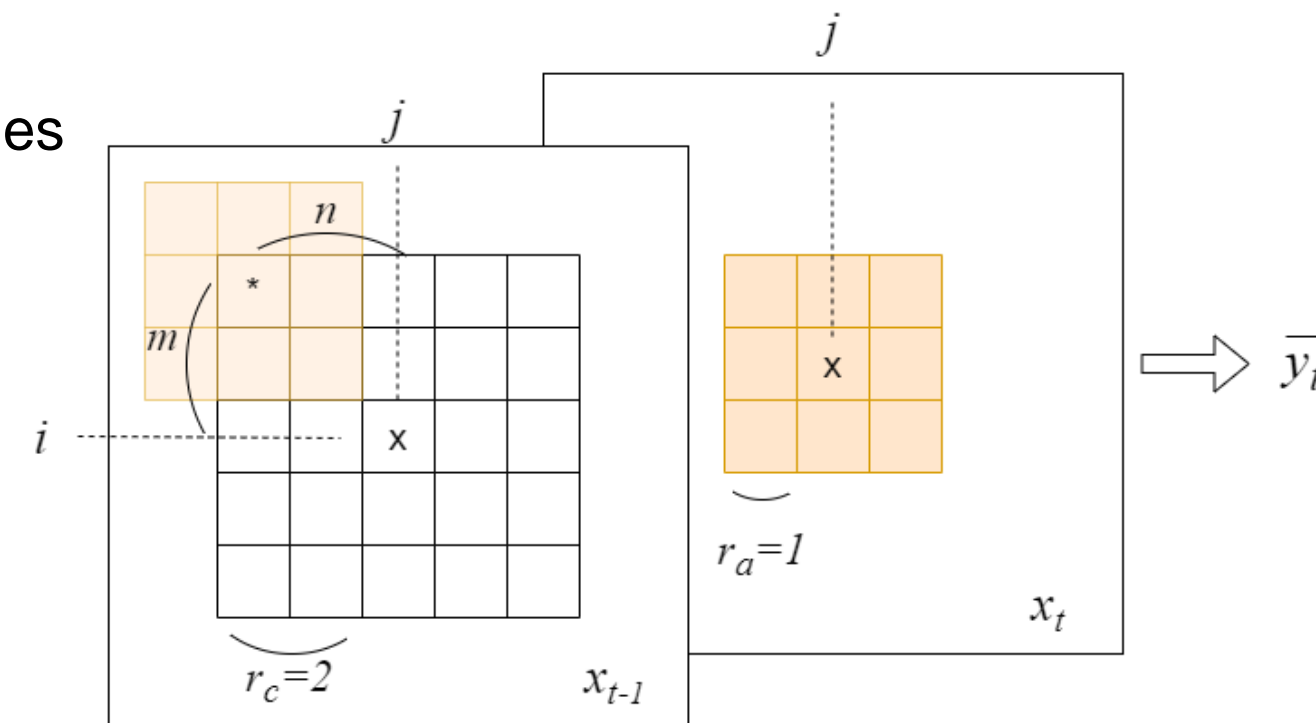
- post-processing

median filtering of the confidence image

- final decision

"confidence value" calculation – the average of the confidence image samples

if confidence value is greater than a threshold, then frame deletion in the current position exists



## Test video set

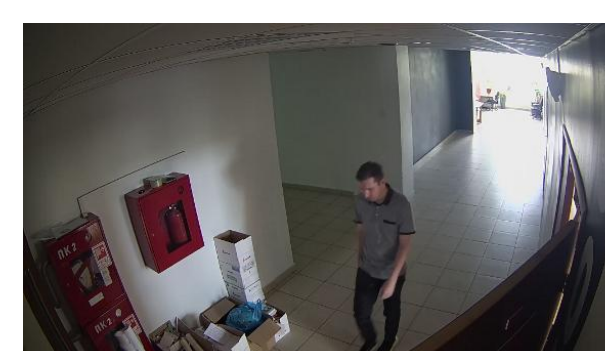
### Test video parameters

	Road	SU_corridor
frame size	1080x1920	1080x1920
fps	100	25
codec	H264-MPEG AVC (part 10)	H264-MPEG AVC (part 10)
GOP	GOP=24 (I,P,B-frames)	GOP=50 (I,P-frames)
video length	1 video more than 1 hour long	5 videos 1-2 minutes long
video particularities	Outdoor camera. Small camera jitter and illumination changes.	Indoor camera. Includes natural and artificial illumination scenes.
source	J. Sochor, R. Juránek, J. Spanhel, L. Marsik, A. Siroky, A. Herout, and P. Zemcik, "Comprehensive Data Set for Automatic Single Camera Visual Speed Measurement," IEEE Transactions on Intelligent Transportation Systems, vol. 20, pp. 1633-1643, 2019.	Falcon Eye FE-IPC-BV2-50pa

### Examples of test video frames

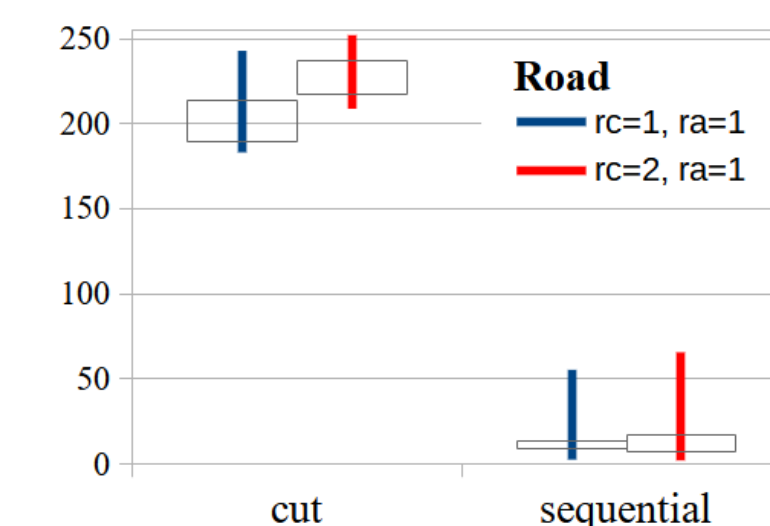


«Road» video

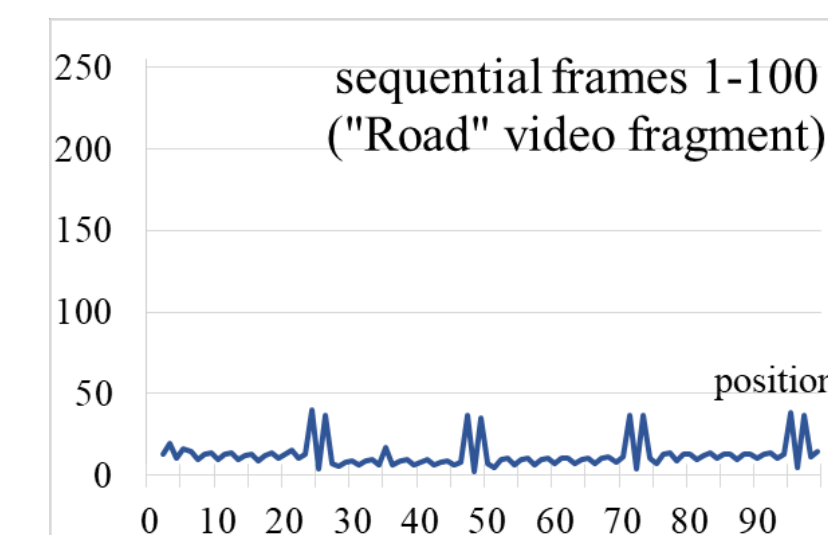


«SU\_corridor» video

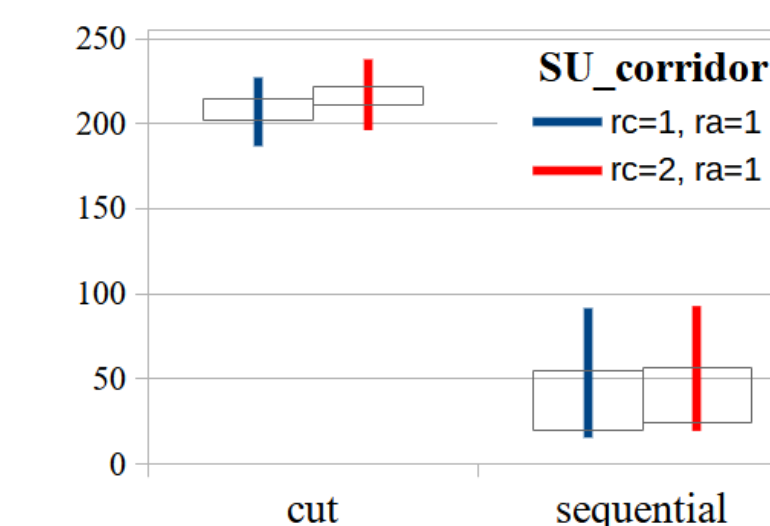
### Statistics for confidence value



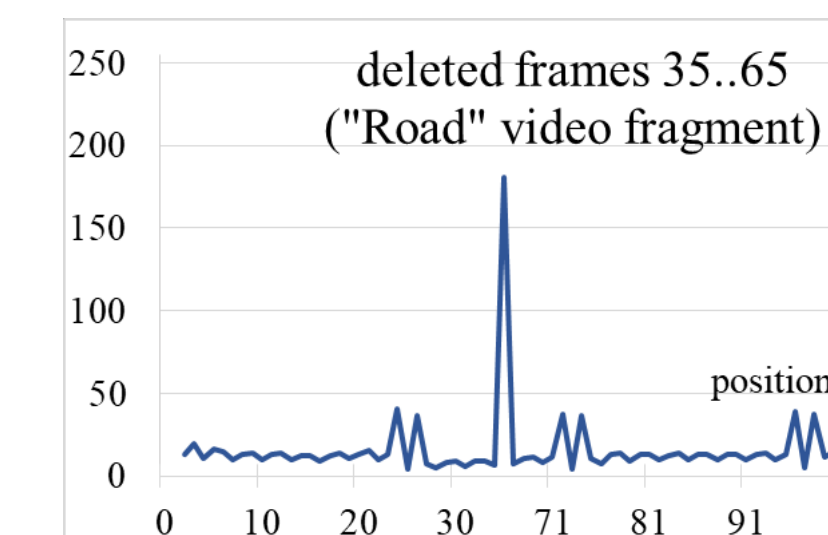
Statistics of the confidence value for the «Road» test video. Good separability of classes «cut» and «sequential».



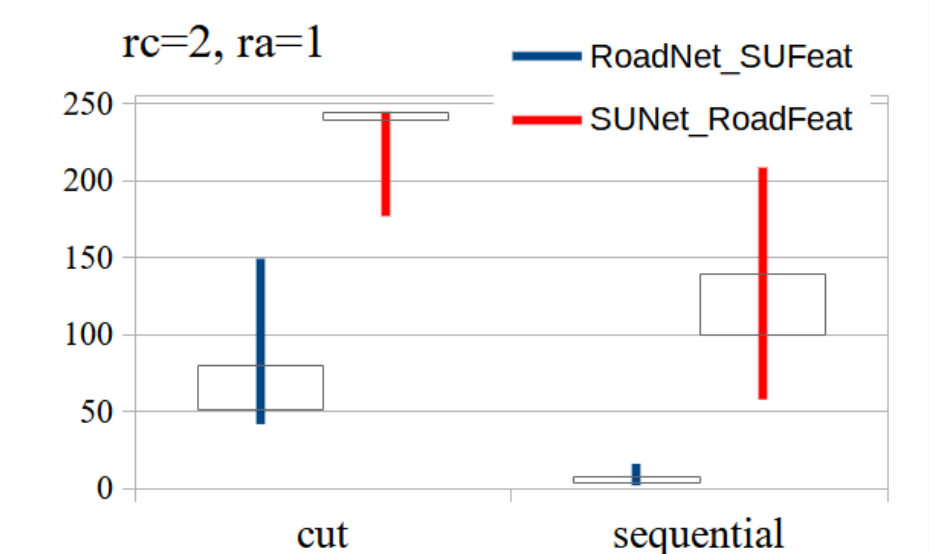
Variation of the confidence value for the «Road» test video fragment. Sequential frames 1..100.



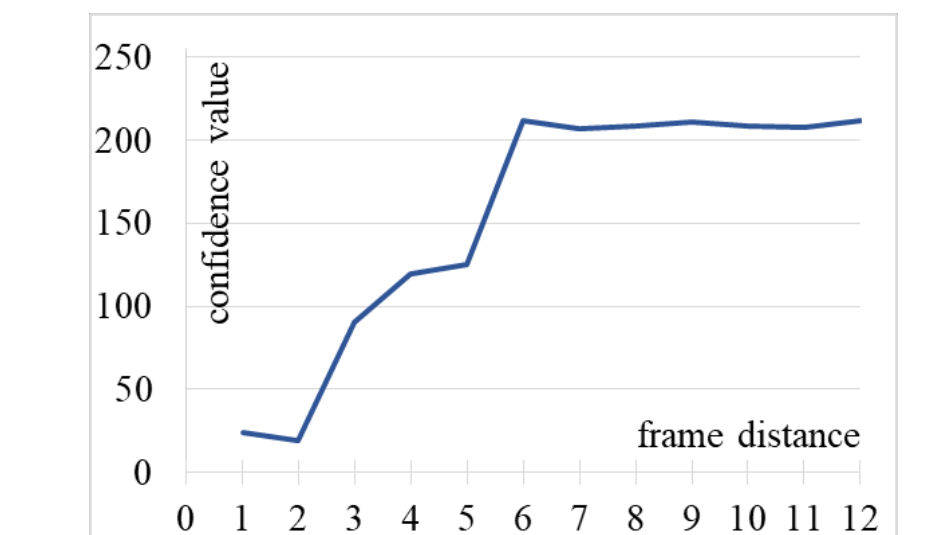
Statistics of the confidence value for the «SU\_corridor» test video set. Good separability of classes «cut» and «sequential».



Variation of the confidence value for the «SU\_corridor» test video fragment. Frames 35-65 were cut from the video fragment.

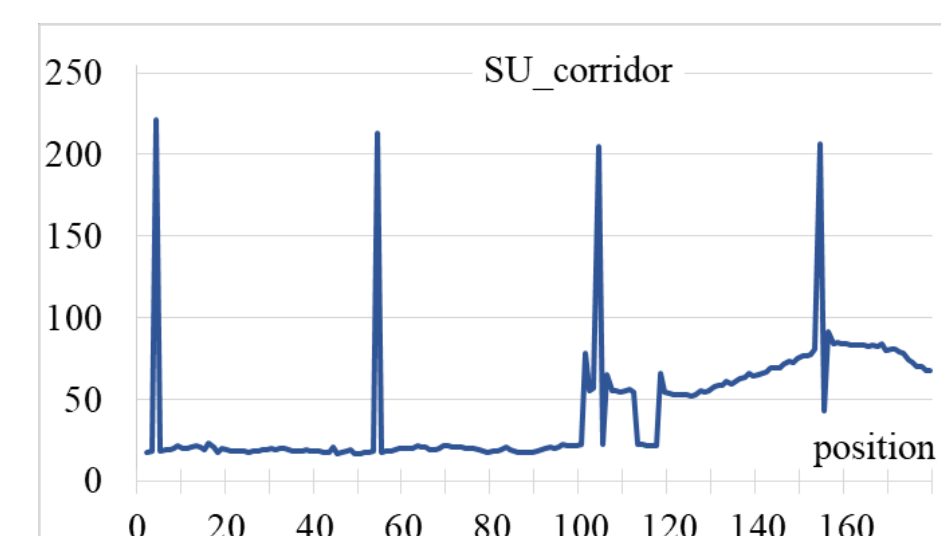


The results of applying the net, tuned for one video, to another video. Poor separability of classes «cut» and «sequential».



The dependence of the confidence value on the distance between frames («Road» video fragment). The removal even a few frames will be detected.

### Restrictions of the method



Variation of the confidence value for the «SU\_corridor» test video fragment. Sequential frames 1..179. False frame deletion detection for every I-frame.

### Conclusions:

- The proposed method contributes to the construction of a universal data protection system in the area where many algorithms configured to track the movement of objects do not work correctly (skipping the frame removal in video with the little or no movement).
- The proposed way of local feature construction makes it possible to take into account both the movement of objects and "small structures", specific to the particular video type (caused by the combination of camera parameters, compression method, and environment).
- Limitations of the method were also revealed, caused by both the unsatisfactory video quality (camera and compression parameters) and the behavior of objects in the frame (overlapping one of the light sources).